

# uPLC examples - Structured text (ST)

To help you get started with the **ST to IL Converter**, we have provided a collection of code examples ranging from basic logic to advanced functions. These snippets demonstrate the correct syntax and best practices for writing Structured Text optimized for our integrated drives.

Please use the ST to IL online converter here:

[https://www.ni-lab.online/new\\_websmart/nilab\\_st\\_converter.php](https://www.ni-lab.online/new_websmart/nilab_st_converter.php)

## Motion controller interaction

- Change the motion table index with a timer (5 different motion tasks):  
[:integrated\\_drive\\_motors:5\\_step\\_motion\\_with\\_timer.zip](#)
- Change the motion table index with the two digital inputs (4 different motion tasks):  
[:integrated\\_drive\\_motors:4\\_step\\_motion\\_with\\_2\\_inputs.zip](#)

## Output control

- Toggle Digital output3 with timer : [:integrated\\_drive\\_motors:output\\_pulse\\_with\\_timer.zip](#)

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