

# CanOPEN over EtherCAT

Mode of operation:

[https://www.nilab.at/dokuwiki/doku.php?id=integrated\\_drive\\_motors:canopen\\_modes](https://www.nilab.at/dokuwiki/doku.php?id=integrated_drive_motors:canopen_modes)

Standard PDOs: [https://www.nilab.at/dokuwiki/doku.php?id=integrated\\_drive\\_motors:can\\_open\\_pdo](https://www.nilab.at/dokuwiki/doku.php?id=integrated_drive_motors:can_open_pdo)

Standard SDOs: [https://www.nilab.at/dokuwiki/doku.php?id=integrated\\_drive\\_motors:canopen\\_sdo](https://www.nilab.at/dokuwiki/doku.php?id=integrated_drive_motors:canopen_sdo)

Errors Codes: [https://www.nilab.at/dokuwiki/doku.php?id=integrated\\_drive\\_motors:canopen\\_error](https://www.nilab.at/dokuwiki/doku.php?id=integrated_drive_motors:canopen_error)

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[https://www.nilab.at/dokuwiki/doku.php?id=gdi\\_ethercat:coe](https://www.nilab.at/dokuwiki/doku.php?id=gdi_ethercat:coe)

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