Xtrapulspack Easy Servoregler

Um den Antrieb für die Arbeit mit NILAB zu konfigurieren, siehe diese Seite:
https://www.nilab.at/dokuwiki/doku.php?id=green_drive_motors:xtrapulspack|

Software für die Parametrierung des Antriebs:
https://www.nilab.at/download/gemdrive-studio-5-36-infranor-drive/?wpdmdl=7376&refresh=67a1d90a4104f1738660106

Für die Steuerung über CANopen-fieldbus laden Sie die EDS hier herunter:
:miniature_motors:eds_file_easy-ak_v1.31.zip

Serielle und CANopen-Kommunikation - X5-Steckverbinder-Pinout

Vorgeschlagener USB-zu-RS232-Konverter: https://ftdichip.com/products/usb-rs232-we-1800-bt_0-0/

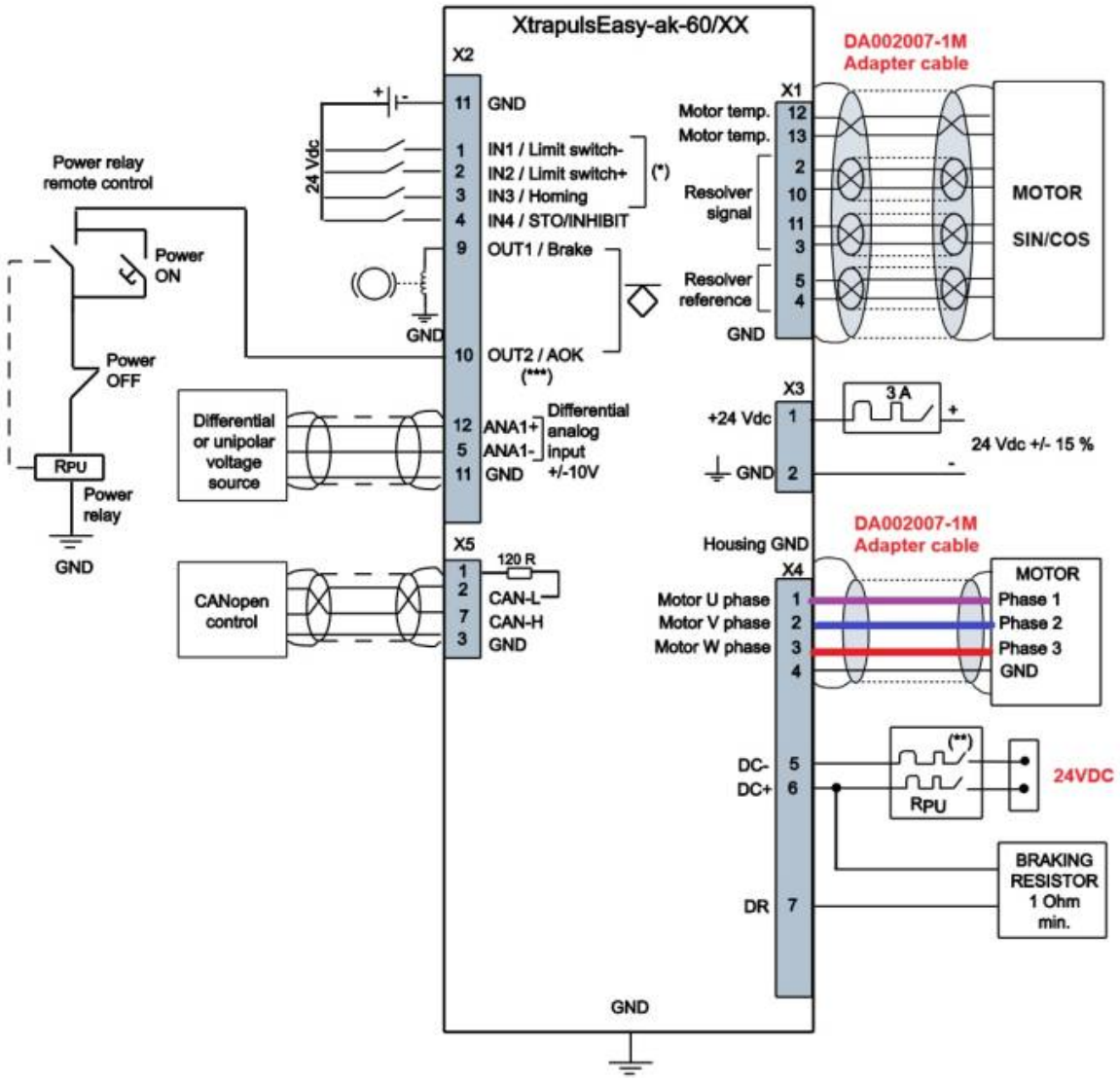
SUB D 9 pin male connector

PIN	FUNCTION	REMARKS
1	Termination resistor	Connect X5.1 to X5.7 to enable the termination resistor
2	CAN-L	Line CAN-L (dominant low)
3	GND	GND signal for CAN communication
4	TXD	Transmit data RS-232
5	GND	GND (shield connection if no 360° connection on the connector). 360° shield connection is highly recommended.
6		Reserved
7	CAN-H	Line CAN-H (dominant high)
8	RXD	Receive data RS-232
9		Reserved

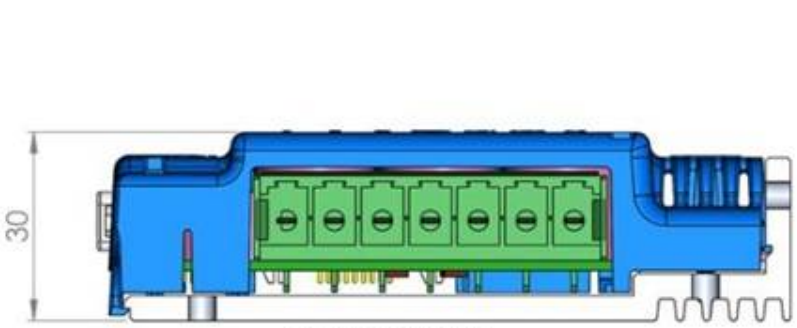
Default parameters for the CANopen bus are:

- Transmission speed of 1 Mb/s,
- Address set at 1,

Motor- und Feedback-Anschlüsse

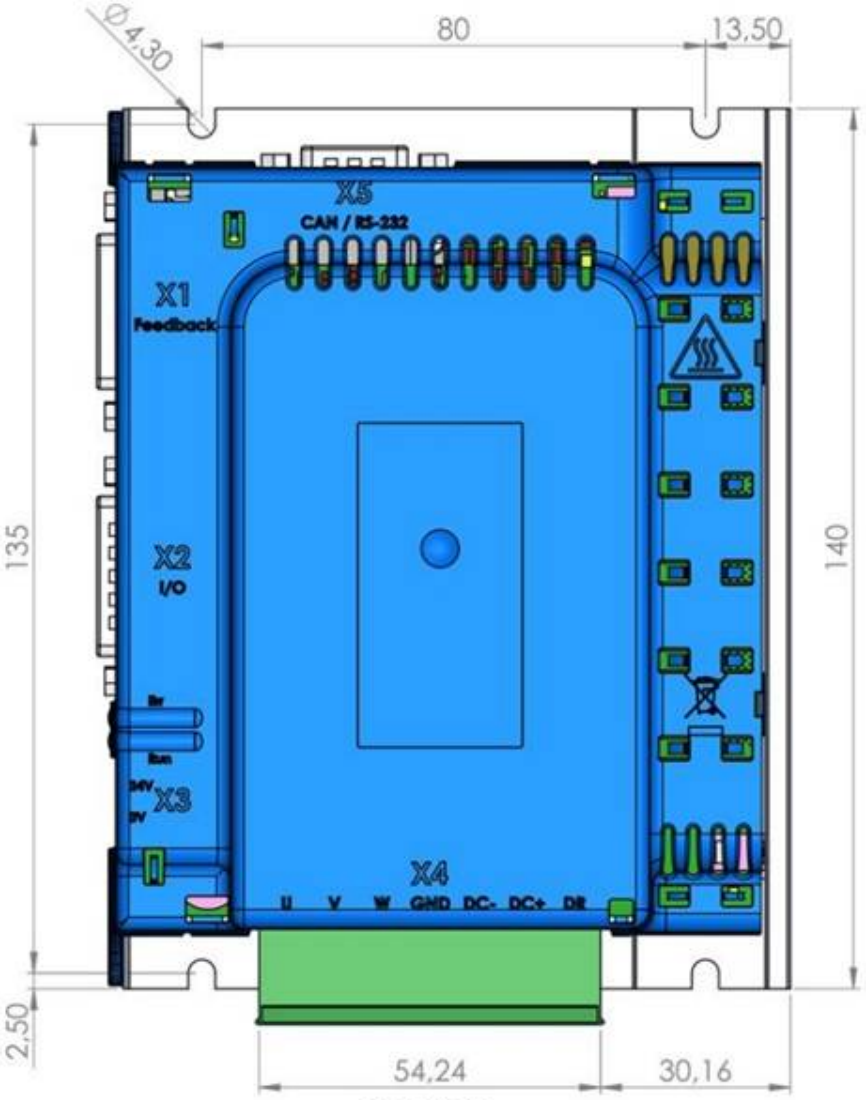


Mechanische Abmessungen und Steckverbinderposition des Servoreglers

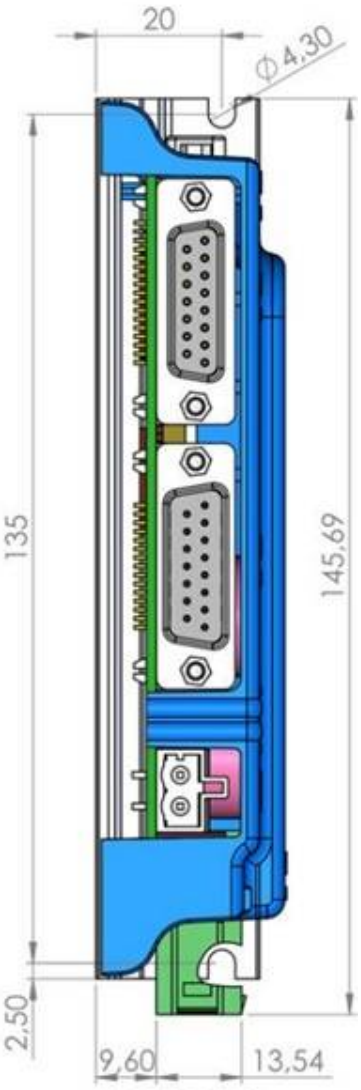


BOTTOM VIEW

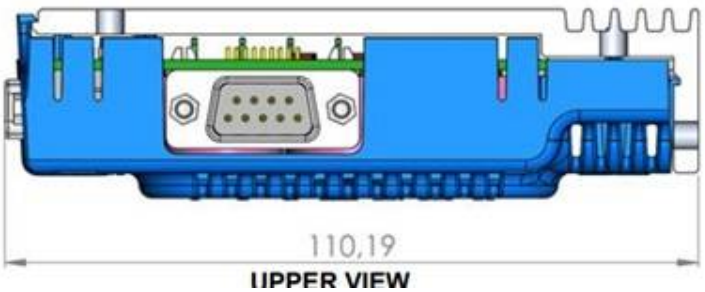




SIDE VIEW



FRONT VIEW



UPPER VIEW

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